

## Year 13 Knowledge Organiser Mechanics

### 1. Moments

Clockwise moment of F about P =	$ F  \times d$
Clockwise moment of F about P =	$ F  \times d \sin \theta$
Coplanar forces	Forces that act in the same plane
Resultant moment	The sum of the moments acting on a body
When a rigid body is in equilibrium...	The resultant force in any direction is 0N and the resultant moment about any point is 0N
Non-uniform rod	The centre of mass is not at midpoint of the rod
When a body is on the point of tilting about a pivot...	The reaction at any other support (or the tension in any other wire or string) is 0

### 2. Forces & Friction

The component of a force	The effect of the force in the direction of motion
The component of a force magnitude F in a certain direction is...	$F \cos \theta$ , where $\theta$ is the size of angle between the force and the direction
Maximum/limiting value	Force at which a stationary object will move
$F_{\max} =$	$\mu R$
	$\mu$ is the coefficient of friction, R is the normal reaction between the two surfaces

### 3. Projectiles

The horizontal motion of a projectile is modelled as having...	Constant velocity ( $a = 0$ )
You can use the formula $s =$	$vt$
The vertical motion of a projectile is modelled as having...	Constant acceleration due to gravity ( $a=g$ )
Horizontal component of the initial velocity for projected particle	$U \cos \alpha$
Vertical component of the initial velocity for projected particle	$U \sin \alpha$
$U =$	Initial velocity
$\alpha =$	Angle above horizontal

A projectile reaches its point of greatest height when the...	Vertical component of its velocity is equal to 0
Time of flight =	$\frac{2U \sin \alpha}{g}$
Time to reach greatest height =	$\frac{U \sin \alpha}{g}$
Range on horizontal plane =	$\frac{U^2 \sin 2\alpha}{g}$
Equation of trajectory	$y = x \tan \alpha - gx^2 \frac{(1 + \tan^2 \alpha)}{2U^2}$
Y	Vertical height of particle
X	Horizontal distance from point of projection
g	Acceleration due to gravity

### 4. Application of Forces

A particle or rigid body is in static equilibrium if...	It is at rest and the resultant force acting on the particle is 0
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# MATHS-MECHANICS

Limiting equilibrium	When a body is on the point of moving
$F_{max}$ is reached when... The force of friction $F$ is such that	The body is in limiting equilibrium $F \leq \mu R$
The direction of the frictional force is opposite to... For a rigid body in static equilibrium	The direction in which the body would move if the frictional force were absent <ul style="list-style-type: none"> <li>• The body is stationary</li> <li>• The resultant force in any direction is 0</li> <li>• The resultant moment is 0</li> </ul>
<b>5. Further Kinematics</b>	
Position vector for particle $r =$	$r_o + vt$
$r_o =$	Position vector for starting point
$v =$	Constant velocity
Displacement from initial position at time $t$	$vt$
Object moving in plane with constant acceleration $v =$	$u + at$
Object moving in plane with constant acceleration $r =$	$ut + \frac{1}{2} at^2$
$u =$	Initial velocity
$a =$	Acceleration
$v =$	Velocity at time $t$
$r =$	Displacement at time $t$
If $r = xi + yj, v =$	$\frac{dr}{dt} = \dot{r} = \dot{x}i + \dot{y}j$
If $r = xi + yj, a =$	$\frac{dv}{dt} = \frac{d^2r}{dt^2} = \ddot{r} = \ddot{x}i + \ddot{y}j$
$v =$	$\int a dt$
$r =$	$\int v dt$